Optimal individualized decision rules using instrumental variable methods

Hongxiang Qiu<sup>1</sup>

Joint work with:

Marco Carone<sup>1</sup>, Ekaterina Sadikova<sup>2</sup>, Maria Petukhova<sup>2</sup>, Ronald C. Kessler<sup>2</sup>, Alex Luedtke<sup>3</sup>

<sup>1</sup>: Dept. of Biostatistics, University of Washington

<sup>2</sup>: Dept. of Health Care Policy, Harvard Medical School

<sup>3</sup>: Dept. of Statistics, University of Washington

비로 서로에 서로에 서랍에 수많이 했다.

- Emerging area of individualized treatment rules (ITR).
- Previous methods assume no unmeasured confounding (e.g., Murphy, 2003; Robins, 2004; Zhao et al., 2012; Chakraborty and Moodie, 2013; Luedtke and van der Laan, 2016b).
  What if there is unmeasured confounding?

- Emerging area of individualized treatment rules (ITR).
- Previous methods assume no unmeasured confounding (e.g., Murphy, 2003; Robins, 2004; Zhao et al., 2012; Chakraborty and Moodie, 2013; Luedtke and van der Laan, 2016b).
  What if there is unmeasured confounding?
- Instrumental variable (IV): another approach to identifying causal effects. Can we use an IV to estimate an optimal ITR?

- Emerging area of individualized treatment rules (ITR).
- Previous methods assume no unmeasured confounding (e.g., Murphy, 2003; Robins, 2004; Zhao et al., 2012; Chakraborty and Moodie, 2013; Luedtke and van der Laan, 2016b).
  What if there is unmeasured confounding?
- Instrumental variable (IV): another approach to identifying causal effects. Can we use an IV to estimate an optimal ITR?
- Example:
  - IV: randomized treatment assignment
  - Treatment: actual treatment status
- Especially interested in settings with a treatment resource constraint (Luedtke and van der Laan, 2016a).

・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・

- At times, direct intervention on treatment may be impossible or expensive.
- Individualized encouragement rule (IER): intervention on IV.
- Evaluate optimal rules: average benefit under optimal rule (compared to a reference rule).

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □



2 Identifying conditions and results

3 Estimation and inference under a locally nonparametric model

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

- Observe iid  $O = (W, Z, A, Y) \sim P_0$ :
  - $W \in W$ : baseline covariates.
  - $Z \in \{0,1\}$ : binary IV.
  - *A* ∈ {0,1}: binary treatment status (treatment vs control).
  - $Y \in \mathbb{R}$ : outcome of interest (larger values are preferable).
- (Stochastic) individualized rule:  $d: W \rightarrow [0,1]$  (prob of treatment)
- Counterfactuals:
  - A(z): potential treatment status corresponding to Z = z
  - Y(z, a): potential outcome corresponding to (Z, A) = (z, a)
- Given treatment resource constraint:  $P_0$ (receiving treatment)  $\leq \kappa$ .

- Relevance:  $|P_0(A = 1 | Z = 1, W) P_0(A = 1 | Z = 0, W)| > \delta^A$
- Exclusion restriction: Y(0, a) = Y(1, a) =: Y(a)
- Independence:  $Z \perp U \mid W$
- Z: IV/encouragement.
- U: unobserved confounder.



< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

For an ITR  $t : W \rightarrow [0, 1]$ , Y(t) := counterfactual outcome under t.

The optimal ITR  $t_0$  solves

```
maximize \mathbb{E}[Y(t)] subject to \mathbb{E}[t(W)] \leq \kappa.
```

The impact of implementing the optimal ITR can be measured via its average treatment effect (ATE) relative to a given reference ITR  $t_r$ :

 $\mathbb{E}[Y(t_0) - Y(t_r)]$ 

For an IER  $e: \mathcal{W} \rightarrow [0,1]$ , A(e) := counterfactual treatment under e.

The optimal IER  $e_0$  solves

```
maximize \mathbb{E}[Y(A(e))] subject to \mathbb{E}[A(e)] \leq \kappa.
```

The impact of implementing the optimal IER can be measured via its average encouragement effect (AEE) relative to a given reference IER  $e_r$ :

 $\mathbb{E}[Y(A(e_0)) - Y(A(e_r))]$ 

Setup and causal estimands



Estimation and inference under a locally nonparametric model

• IV  $\rightarrow$  outcome effect (conditional average encouragement effect):

$$\Delta_0^{Y}(w) = \mathsf{E}_0[Y|Z = 1, W = w] - \mathsf{E}_0[Y|Z = 0, W = w]$$

• Treatment regression:

$$\mu_0^A(z,w) = \mathsf{E}_0[A \mid Z = z, W = w]$$

 $\bullet \ IV \rightarrow treatment \ effect:$ 

$$\Delta_0^A(w) = \mu_0^A(1, w) - \mu_0^A(0, w) = \mathsf{E}_0[A \mid Z = 1, W = w] - \mathsf{E}_0[A \mid Z = 0, W = w]$$

• Wald estimand:

$$\Delta_0(w) = \frac{\Delta_0^Y(w)}{\Delta_0^A(w)} = \frac{\mathsf{E}_0[Y \mid Z = 1, W = w] - \mathsf{E}_0[Y \mid Z = 0, W = w]}{\mathsf{E}_0[A \mid Z = 1, W = w] - \mathsf{E}_0[A \mid Z = 0, W = w]}$$

**Key identifying conditions** (slightly relaxed version of Wang and Tchetgen Tchetgen (2018)):

- $Y(a) \perp (A, Z) \mid (W, U).$
- One of the following sets of conditions holds:
  - (1) (a) (Uncorrelated IV)  $Cov(Y(0), Z \mid W) = 0$ 
    - (b) (No unmeasured treatment-outcome effect modification)

$$\mathbb{E}\left[Y(1) - Y(0) \mid W, U\right] = \mathbb{E}\left[Y(1) - Y(0) \mid W\right]$$

- (2) (a) (Independent IV)  $Z \perp U \mid W$ 
  - (b) (Independent compliance)

$$\mathbb{E}[A(Z) \mid Z = 1, W, U] - \mathbb{E}[A(Z) \mid Z = 0, W, U] \\= \mathsf{E}_0[A \mid Z = 1, W] - \mathsf{E}_0[A \mid Z = 0, W]$$

ATE can be written as a summary of  $P_0$ .

Theorem (Identification of ATE)

• 
$$\mathbb{E}[Y(1) - Y(0) \mid W] = \Delta_0(W)$$

• 
$$\mathbb{E}[Y(t) - Y(t_r)] = \mathsf{E}_0[\{t(W) - t_r(W)\}\Delta_0(W)]$$
 for any ITR  $t$ 

The optimization problem in ITR t is equivalent to

```
maximize E_0[t(W)\Delta_0(W)] subject to E_0[t(W)] \le \kappa.
```

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

# Case I: optimal ITR

What does an optimal ITR look like?

▲□▶ ▲圖▶ ▲目▶ ▲目▶ 三目目 のへで

## Case I: optimal ITR

What does an optimal ITR look like?





- 1. Sort subgroups according to  $\Delta_0(W)$  (from high to low).
- 2. Assign treatment to those with highest (and positive) conditional ATE  $\Delta_0(W)$  until treatment runs out.

$$t_0(w) = I\left\{\Delta_0(w) > \tau_0^T\right\}$$

<□> <同> <同> <目> <日> <同> <日> <同> <日> <日> <同> <日> <日 <0 <0

Key identifying condition:  $Z \perp (A(z), Y(a)) \mid W$ 

AEE can be written as a summary of  $P_0$ .

Theorem (Identification of AEE)

•  $\mathbb{E}[Y(A(1)) - Y(A(0)) | W] = \Delta_0^Y(W)$ 

•  $\mathbb{E}\left[Y(A(e)) - Y(A(e_r))\right] = \mathsf{E}_0\left[\left\{e(W) - e_r(W)\right\}\Delta_0^Y(W)\right]$  for any IER e

<ロ> <日> <日> <日> <日> <日> <日> <日</p>

The optimization problem in IER e is equivalent to

 $\begin{array}{ll} \mbox{maximize} & {\sf E}_0[e(W)\Delta_0^Y(W)] \\ \mbox{subject to} & {\sf E}_0[e(W)\mu_0^A(1,W) + (1-e(W))\mu_0^A(0,W)] \leq \kappa \ , \end{array}$ 

namely,

maximize 
$$E_0[e(W)\Delta_0^Y(W)]$$
  
subject to  $E_0[e(W)\Delta_0^A(W)] \le \kappa - E_0[\mu_0^A(0, W)]$ ,

Assume that  $\Delta_0^A > 0$  and  $\kappa - \mathsf{E}_0[\mu_0^A(0, W)] > 0$ .

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

What does an optimal IER look like?

▲□▶ ▲圖▶ ▲目▶ ▲目▶ 三目目 のへで

What does an optimal IER look like?

View as a fractional knapsack problem:

- Subgroup with same W: item
- Conditional AEE:  $\Delta_0^Y(W) =$ value
- Additional proportion treated:  $\Delta_0^A(W) =$ weight
- Max additional proportion treated:  $\kappa - E_0[\mu_0^A(0, W)] = \text{total weight capacity}$
- $\xi_0(W) := \Delta_0^Y(W) / \Delta_0^A(W) =$  unit value



- 1. Sort subgroups according to  $\xi_0(W)$  from high to low
- 2. Assign encouragement to treatment to those with highest (and positive)  $\xi_0(W)$  until treatment runs out

$$e_0(w) = I\left(\xi_0(w) > \tau_0^E\right)$$

Setup and causal estimands

2 Identifying conditions and results

3 Estimation and inference under a locally nonparametric model

- Goal: estimate  $\Phi(P_0)$  (ATE, AEE)
- Seemingly natural approach:
  - Estimate  $P_0$  with  $\tilde{P}_n$
  - Plug in: estimate  $\Phi(P_0)$  with  $\Phi(\tilde{P}_n)$
- Problem: typically inefficient and not asymptotically normal.
- Efficient and asymptotically normal plug-in estimator using TMLE.
- Construct Wald CI based on asymptotic variance.

<□> <同> <同> <目> <日> <同> <日> <日> <日> <日> <日> <日> <日> <日 < □ < 0 <0

- 1. Flexibly estimate relevant regression functions.
- 2. Estimate optimal ITR/IER with sample analogue.
- 3. Targeted estimation of ATE/AEE. The resulting estimator is asymptotically normal under conditions.

Estimands:

- Resource constrained AEE: AEE of  $e_0$  with  $\kappa=0.68$
- ATE: ATE of  $t_0$  without resource constraint ( $\kappa = 1$ )
- Resource constrained ATE: ATE of  $t_0$  with  $\kappa = 0.25$

Data-generating mechanism has strong unmeasured treatment-outcome confounding.

Use sample splitting when estimating the optimal rule

- avoid a main source of finite-sample positive bias
- possible finite-sample negative bias
- valid 97.5% confidence lower bound, even under poorly estimated optimal rule

### Simulation: AEE with resource constraints

Performance measure	Sample size	IV
95% Wald CI coverage	500	71%
	1000	74%
	4000	84%
	16000	90%
97.5% confidence lower	500	96%
bound coverage	1000	98%
	4000	98%
	16000	98%



Hongxiang Qiu et al. (U Washington)

# Simulation: ATE

Performance measure	Sample size	IV	Confounder
95% Wald CI coverage	200	97%	3%
	500	95%	< 1%
	1000	93%	< 1%
	2000	92%	< 1%
97.5% confidence lower	200	> 99%	3%
bound coverage	500	> 99%	< 1%
	1000	> 99%	< 1%
	2000	> 99%	< 1%



Hongxiang Qiu et al. (U Washington)

### Simulation: ATE with resource constraints

Performance measure	Sample size	IV	Confounder
95% Wald CI coverage	200	96%	83%
	500	95%	84%
	1000	93%	87%
	2000	94%	88%
97.5% confidence lower	200	> 99%	97%
bound coverage	500	> 99%	97%
	1000	> 99%	96%
	2000	> 99%	92%



Hongxiang Qiu et al. (U Washington)

#### Discussion

- Estimators of optimal individualized treatment/encouragement rule using an IV under treatment resource constraints.
- Inference on average causal effects of the optimal rule under a locally nonparametric model.
- Cui and Tchetgen Tchetgen (2020) studied a similar problem with IV.
  - Cui and Tchetgen Tchetgen needed not consider intervention on encouragement or resource constraints.
  - Weaker identifying conditions for optimal ITR (not ATE).
  - Cui and Tchetgen Tchetgen's optimal ITR among compliers = our optimal IER
- Han (2020) and Cui and Tchetgen Tchetgen (2021) proposed even weaker identifying conditions for optimal ITR.
- Sun et al. (2021) studied a similar problem with random treatment cost and treatment cost constraint.
  - Our methods for IER and AEE can be readily adapted to this setting.
  - We additionally provide statistical inference on AEE.

Work based on

Qiu, H., M. Carone, E. Sadikova, M. Petukhova, R. C. Kesslar, and A. Luedtke (2020). Optimal individualized decision rules using instrumental variable methods. *JASA 116*(553), 174–191.

Qiu, H., M. Carone, A. Luedtke (publicly available soon). Estimation of optimal individualized encouragement rules and statistical inference about their effects under treatment resource constraints

- Chakraborty, B. and E. E. Moodie (2013). *Statistical Methods for Dynamic Treatment Regimes*. Statistics for Biology and Health. New York, NY: Springer New York.
- Cui, Y. and E. Tchetgen Tchetgen (2020). A Semiparametric Instrumental Variable Approach to Optimal Treatment Regimes Under Endogeneity. *Journal of the American Statistical Association*.
- Cui, Y. and E. Tchetgen Tchetgen (2021). On a necessary and sufficient identification condition of optimal treatment regimes with an instrumental variable. *Statistics & Probability Letters*, 109180.
- Han, S. (2020). Comment: Individualized Treatment Rules Under Endogeneity. *Journal of the American Statistical Association*.
- Luedtke, A. R. and M. J. van der Laan (2016a). Optimal Individualized Treatments in Resource-Limited Settings. *International Journal of Biostatistics* 12(1), 283–303.
- Luedtke, A. R. and M. J. van der Laan (2016b). Statistical inference for the mean outcome under a possibly non-unique optimal treatment strategy. *Annals of Statistics* 44(2), 713–742.
- Murphy, S. A. (2003). Optimal dynamic treatment regimes. Journal of the Royal Statistical Society: Series B (Statistical Methodology) 65(2), 331–355.
- Robins, J. M. (2004). Optimal Structural Nested Models for Optimal Sequential Decisions. pp. 189–326. Springer, New York, NY.

Sun, H., S. Du, and S. Wager (2021). Treatment Allocation under Uncertain Costs. arXiv preprint arXiv:2103.11066v1.

- Wang, L. and E. Tchetgen Tchetgen (2018). Bounded, efficient and multiply robust estimation of average treatment effects using instrumental variables. *Journal of the Royal Statistical Society: Series B (Statistical Methodology) 80*(3), 531–550.
- Zhao, Y., D. Zeng, A. J. Rush, and M. R. Kosorok (2012). Estimating Individualized Treatment Rules Using Outcome Weighted Learning. *Journal of the American Statistical Association 107*(499), 1106–1118.

Thank you! Questions?

For any distribution P on observed data<sup>\*</sup>, define

•  $\mu_P^Z : w \mapsto \mathsf{E}_P(Z \mid W = w)$  (IV propensity)

• 
$$\mu_P^A$$
 :  $(z, w) \mapsto \mathsf{E}_P(A \mid Z = z, W = w)$  (Treatment regression)

• 
$$\mu_P^Y$$
 :  $(z, w) \mapsto \mathsf{E}_P(Y \mid Z = z, W = w)$  (Outcome regression)

• 
$$\Delta_P^A: w \mapsto \mu_P^A(1,w) - \mu_P^A(0,w)$$
 (IV  $\rightarrow$  treatment effect)

• 
$$\Delta_P^Y : w \mapsto \mu_P^Y(1, w) - \mu_P^Y(0, w)$$
 (IV  $\rightarrow$  outcome effect)

• 
$$\Delta_P : w \mapsto \Delta_P^Y(w) / \Delta_P^A(w)$$
 (Wald estimand)

\*For  $P_0$ , we use 0 instead of  $P_0$  in the subscript.

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

#### Theorem (Identifying optimal ITR)

With  $\eta_0^T := \inf \{\eta : P_0(\Delta_0(W) > \eta) \le \kappa\}$  and the threshold  $\tau_0^T := \max \{\eta_0^T, 0\}$ , the optimal ITR is

$$t_{0}(w) := \begin{cases} \frac{\kappa - P_{0} \{ \Delta_{0}(W) > \tau_{0}^{T} \}}{P_{0} \{ \Delta_{0}(W) = \tau_{0}^{T} \}} & : \Delta_{0}(w) = \tau_{0}^{T} > 0, \\ P_{0} \{ \Delta_{0}(W) = \tau_{0}^{T} \} > 0 \\ I \{ \Delta_{0}(w) > \tau_{0}^{T} \} & : otherwise. \end{cases}$$

#### Theorem (Identifying optimal IER)

With  $\eta_0^E := \inf \left\{ \eta : \mathsf{E}_0 \left[ I(\xi_0(W) > \eta) \Delta_0^A(W) \right] \le \kappa - \mathsf{E}_0[\mu_0^A(0, W)] \right\}$  and  $\tau_0^E := \max \left\{ \eta_0^E, 0 \right\}$ , the optimal IER is

$$e_{0}(w) = \begin{cases} \frac{\kappa - \mathsf{E}_{0}[\mu_{0}^{A}(0,W)] - \mathsf{E}_{0}[I(\xi_{0}(W) > \tau_{0}^{E})\Delta_{0}^{A}(W)]}{\mathsf{E}_{0}[I(\xi_{0}(W) = \tau_{0}^{E})\Delta_{0}^{A}(W)]} & :\xi_{0}(w) = \tau_{0}^{E} > 0, \\ \mathsf{E}_{0}\left[I(\xi_{0}(W) = \tau_{0}^{E})\bar{\mu}_{0}^{A}(W)\right] > 0 \\ I\left(\xi_{0}(w) > \tau_{0}^{E}\right) & : otherwise. \end{cases}$$

<□> <同> <同> <目> <日> <同> <日> <日> <日> <日> <日> <日> <日> <日 < □ < 0 <0